Collective Motions of Animals and Robots 2024, May 27 – 31

https://lstu.fr/collectivecargese24

Preliminary program

Monday 27

Morning

09:00 Welcome 09:15 - 10:30 Iker Zuriguel Bottleneck flow of macroscopic active matter: animals and robots as a benchmark to understand pedestrian evacuations.

11:00 - 12:15 Leticia Cugliandolo *Phases and topological defects in passive and active systems in two dimensions.*

Afternoon

14:00 - 15:15 Marina Papadopoulou Animal groups into the Swarm-Verse: understanding collective motion across species & ecological contexts 15:30 - 16:45 Short presentations

18:00 Welcome Party

Tuesday 28

Morning

09:15 - 10:30 Bertrand Maury Paradoxical effects in collective motions : Capacity Drop and Faster is Slower effect

11:00 - 12:15 Alexandre Nicolas How to model the dynamics of pedestrians? -- Walking a fine line between game theory, physics and transportation science

Afternoon

14:00 -15 :15 Julien Pettré *Modelling and simulation of human crowds: the emergence of machine learning models and the question of training data.* 15:30 - 16:30 Short presentations

18:00 – 19:00: Public conference (In French): Clément Sire Quand de pauvres petits poissons sont confrontés à l'IA, la réalité virtuelle, des robots et des drones !

Wednesday 29

Morning

9:15 - 10:30 Franck Rufier *From individual to collective behaviors based on optical flow* 11:00 - 12:15 Short presentations

Afternoon

14 :00 - 15 :15 Cécile Cottin Bizonne *Collective Motion: From Active Colloids to Driven Bacteria.* 15 :30 - 17 :00 Short presentations

18:00 Posters party

Thursday 30

Morning

09:15 - 10 :30 Guy Theraulaz *Data-driven modeling of collective behavior in schooling fish* 11:00 - 12:15 Ramiro Godoy-Diana *Collective fish swimming dynamics: insights from laboratory experiments*

Afternoon

14:00 - 15:15 Gil Ariel *Bacterial swarming: experiments and modelling* 15 :30 - 17 :00 Short presentations

18:00 Poster & free discussion

20 :00 - Barbecue

Friday 31

Morning

09:15 - 10:30 Stefania Melillo Characterization of lab-based swarms of Anopheles gambiae mosquitoes

11:00 - 12:15 Hamid Kellay From active and motile particles to flexible, deformable, and motile superstuctures : a new type of soft robot

Afternoon

14:00 - 15:15 Clément Sire *Measuring the social interactions between fish and a robot-fish*15:30-16:30 Short presentations16 :30 General conclusions.